

## **Mini-Rotary Actuator**

## Series CRJ

Rack-and-Pinion Type/Size: 05, 1



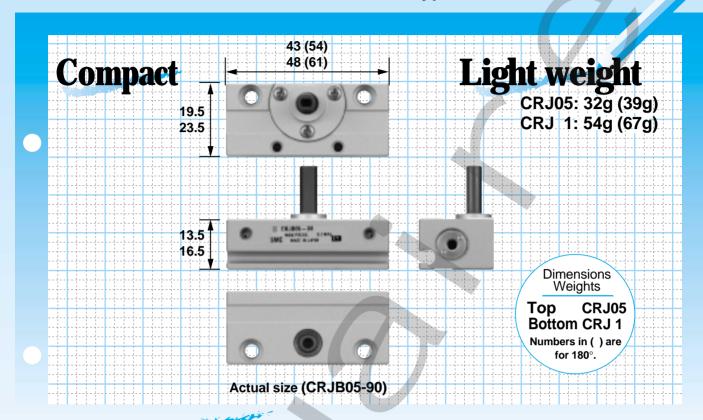
In our pursuit of excellence in size and weight reduction, we proudly announce the release of the Series CRJ Mini-Rotary Actuator!





## Mini-Rotary Actuator Series CRJ

Rack-and-Pinion Type/Size: 05, 1

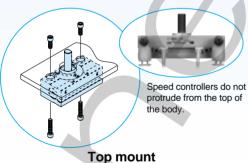


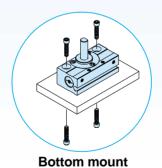
## Flexible mounting

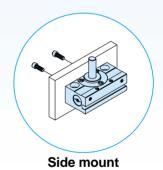
A new compact body design not only reduces overall space requirements, but also achieves space savings in wiring and piping.

Ease in mounting is maximized thanks to the merits of the new compact body.

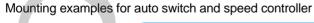
#### Free mount

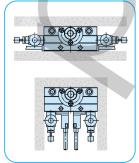


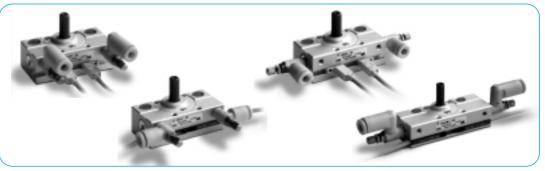




Wiring and piping direction can be selected depending on mounting conditions.



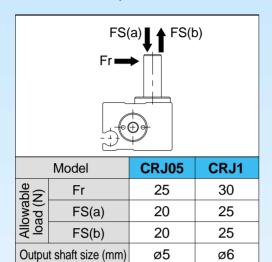


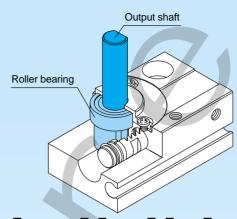




## Improved allowable load

Large roller bearing and large diameter output shaft add to overall compactness while ensuring high rigidity.

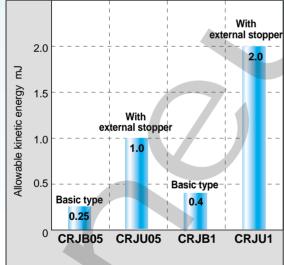




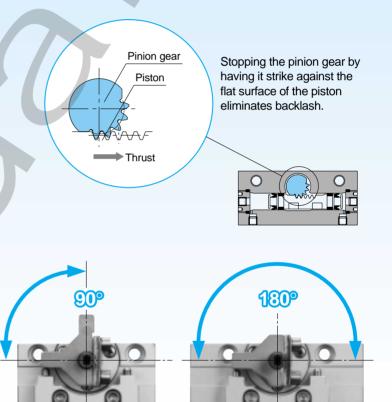
## Reduced backlash

Even with a single rack design, the use of a special construction minimizes backlash.

# With external stopper/Series CRJU 4 to 5 times allowable kinetic energy (Basic type compared to CRJB) With







### **Variations**

Series			Rotatio	n angle		Port location	Auto switch	1
Series	•	90°	100°	180°	190°	Portiocation	Auto Switch	
	CRJB05	•	•	•	•			
Basic type	CRJB 1	•	•	•	•	Front port	D-F8	
With external	CRJU05	•	_	•	_	Side port	D-F9	
stopper	CRJU 1	•	_	•	_			



#### ORDER

### Series CRJ

## **Model Selection**

Calculation **Procedure** Example **Operating conditions** List all possible operating conditions according to the mounting position. Model used Operating pressure Mounting position Fs(b) Fs(a) Load type Ts (N·m) Tf (N·m) Ta (N·m) Load configuration • Rotation time t (s) Rotary actuator: CRJB05-90 Pressure: 0.4MPa Rotation angle Mounting orientaion: Vertical Type of load: Inertial load Ta · Load mass m (kg) Load 1 configuration: 20mm x 10mm (rectangular plate) • Distance between central axis Load 2 configuration: 5mm x 5mm (square plate) and center of gravity H (mm) Rotation time t: 0.2s Rotation angle: 90° Load 1 mass m1: 0.03kg Load 2 mass m2: 0.006kg Distance between central axis and center of gravity H: 7mm Required torque Confirm the type of load as shown Inertial load Effective torque ≥ Ts below, and select an actuator that  $10 \times Ta = 10 \times I \times \dot{\omega}$ Effective torque  $\geq$  (3 to 5) x Tf satisfies the required torque. =  $10 \times 1.57 \times 10^{-6} \times (2 \times (\pi/2)/0.2^2)$ Effective torque ≥ 10 x Ta • Static load: Ts = 0.0012N·m < Effective torque Effective torque Resistance load: Tf Load types Note) I substitutes for 5, the value for inertial moment. • Inertial load: Ta **Rotation time** Confirm that it is within the rotation adjustment time range. 0.1 to 0.5s/90° 0.2s/90° OK Allowable load Confirm that the radial load, Thrust load: m x 9.8 ≤ Allowable load  $(0.03 + 0.006) \times 9.8 = 0.35N < Allowable load$ OK thrust load and moment are within the allowable ranges. Allowable load **Inertial moment** Find the load's inertial moment "I"  $I_1 = m x (a^2 + b^2)/12$  $I_1 = 0.03 \text{ x } (0.02^2 + 0.01^2)/12 = 1.25 \text{ x } 10^{-6} \text{kg} \cdot \text{m}^2$ for the energy calculation.  $I_2 = m x (a^2 + b^2)/12 + m x H^2$  $I_2 = 0.006 \times (0.005^2 + 0.005^2)/12 + 0.006 \times 0.007^2$  $= 0.32 \times 10^{-6} \text{kg} \cdot \text{m}^2$  $I = 1.25 \times 10^{-6} + 0.32 \times 10^{-6}$ Inertial moment  $= 1.57 \times 10^{-6} \text{kg} \cdot \text{m}^2$ Kinetic energy



 $1/2 \times 1.57 \times 10^{-6} \times (2 \times (\pi/2)/0.2)^{2}$ 

= 0.00019J = 0.19mJ < Allowable energy

 $1/2 \times I \times \omega^2 \le \text{Allowable energy}$ 

 $\omega = 2\theta/t$  ( $\omega$ : Terminal angular velocity)

θ: Rotation angle (rad)
t: Rotation time (s)

Allowable kinetic energy/Rotation time

value.

Confirm that the load's kinetic

energy is within the allowable





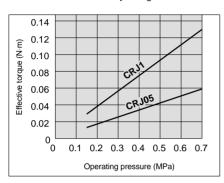
## Model Selection Series CRJ

#### **Effective Torque**

Unit: N·m

Size		Operating pressure (MPa)									
	0.15	0.2	0.3	0.4	0.5	0.6	0.7				
05	0.013	0.017	0.026	0.034	0.042	0.050	0.059				
1	0.029	0.038	0.057	0.076	0.095	0.11	0.13				

Note) Effective torque values are representative values. They are not guaranteed values. Use them only as a guide.



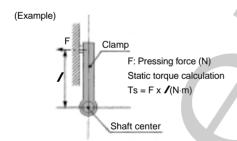
#### **Load Types**

#### Static load: Ts

#### Definition for our purposes:

A load that requires pressing force only, as represented by the clamp.

If the mass of the clamp itself in the drawing below is considered in the calculations, it should be regarded as an inertial load.



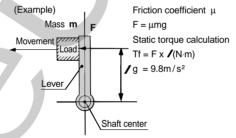
#### • Resistance load: Tf

#### Definition for our purposes:

A load that is affected by external forces such as friction or gravity. Since the purpose is to move the load, and speed adjustment is necessary, allow an extra margin of 3 to 5 times in the effective torque.

\* Actuator effective torque ≥ (3 to 5) x Tf

If the mass of the lever itself in the drawing below is considered in the calculations, it should be regarded as an inertial load.



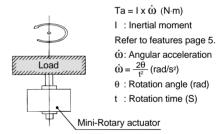
#### • Inertial load:

#### Definition for our purposes:

The load that is actually rotated by the actuator. Since the purpose is to rotate the load, and speed adjustment is necessary, allow an extra margin of 10 times or more in the effective torque.

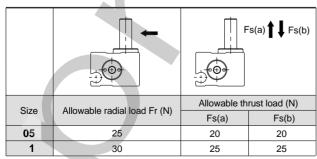
\* Actuator effective torque ≥ S x Ta (S is 10 times or more)

#### Accelerating torque calculation



#### **Allowable Load**

Set the load and moment applied to the shaft within the allowable values provided in the table below. (Operation above the allowable values can cause adverse effects on service life, such as play in the shaft and loss of accuracy.)





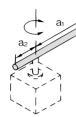


#### **Inertial Moment Formulas**

I: Inertial moment kg·m², m: Load mass kg

#### 1. Thin shaft

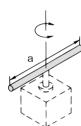
Position of rotational axis: Perpendicular to the shaft anywhere along its length



$$I = m_1 x \frac{a_1^2}{3} + m_2 x \frac{a_2^2}{3}$$

#### 2. Thin shaft

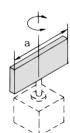
Position of rotational axis: Through the shaft's center of gravity



$$I = m x \frac{a^2}{12}$$

#### 3. Thin rectangular plate (rectangular parallelopiped)

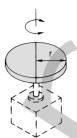
Position of rotational axis: Through the plate's center of gravity



$$I = m x \frac{a^2}{12}$$

#### 6. Cylinder (including thin round plate)

Position of rotational axis: Through the plate's central axis



$$I = m x \frac{r^2}{2}$$

#### 7. Solid sphere

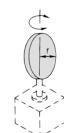
Position of rotational axis: Through the sphere's diameter



$$I = m x \frac{2r^2}{5}$$

#### 8. Thin round plate

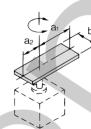
Position of rotational axis: Through the plate's diameter



$$I = m x \frac{r^2}{4}$$

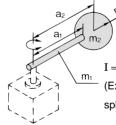
#### 4. Thin rectangular plate (rectangular parallelopiped)

Position of rotational axis: Perpendicular to the plate through one end (also the same in the case of a thicker plate)



$$I = m_1 x \frac{4a_1^2 + b^2}{12} + m_2 x \frac{4a_2^2 + b^2}{12}$$

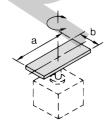
#### 9. Load at the end of lever



 $I = m_1 x \frac{a_1^2}{3} + m_2 x a_2^2 + K$ (Example) When the shape of m2 is a sphere, refer to 7 above. K =  $m_2 x \frac{2r^2}{5}$ 

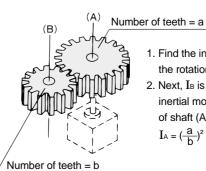
#### 5. Thin rectangular plate (rectangular parallelopiped)

Position of rotational axis: Through the center of gravity and perpendicular to the plate (also the same in the case of a thicker plate)



$$I = m x \frac{a^2 + b^2}{12}$$

#### 10. Gear transmission



- 1. Find the inertial moment  $I_{\mbox{\scriptsize B}}$  for
- 2. Next,  $I_{\mbox{\scriptsize B}}$  is entered to find the inertial moment  $I_{\text{A}}$  for the rotation of shaft (A) as

the rotation of shaft (B).

$$I_A = \left(\frac{a}{b}\right)^2 \times I_B$$





## Model Selection Series CRJ

#### Kinetic Energy/Rotation Time

Even in cases where the torque required for rotation of the load is small, damage to internal parts may result from the inertial force of the load.

Take into account the load's inertial moment and rotation time during operation when making your model selection. (The inertial moment and rotation time charts can be used for your convenience in making model selections.)

#### 1. Allowable kinetic energy and rotation time adjustment range

From the table below, set the rotation time within the proper adjustment range for stable operation. Note that slow speed operation exceeding the rotation time adjustment range, may lead to sticking or stopping of operation.

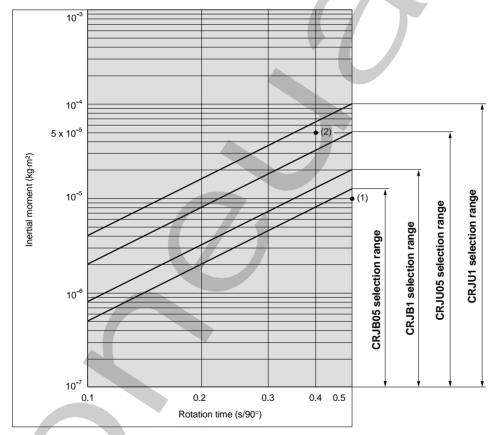
Si	ze			Allowable kinetic energy mJ	Rotation time adjustment range for stable operation s/90°
0	)5	Basic type	CRJB05	0.25	
U	13	With external stopper	CRJU05	1.0	0.1 to 0.5
	1	Basic type	CRJB 1	0.40	0.1 10 0.5
	•	With external stopper	CRJU 1	2.0	

#### 2. Inertial moment calculation

Since the formulas for inertial moment differ depending on the configuration of the load, refer to the inertial moment calculation formulas on the preceding page.

#### 3. Model selection

Select models by applying the inertial moment and rotation time that you have calculated to the chart below.



#### 1. <How to read the chart>

- Inertial moment ....... 1 x 10<sup>-5</sup>kg⋅m²
- Rotation time ...... 0.5s/90°

CRJB05 is selected in this case.

#### 2. <Calculation example>

Load configuration: A cylinder of radius 0.05m and mass 0.04kg

Rotation time: 0.4s/90°

 $I = 0.04 \times 0.05^{2}/2 = 5 \times 10^{-5} \text{kg} \cdot \text{m}^{2}$ 

In the inertial moment and rotation time chart, find the intersection of the lines extended from the points corresponding to 5 x  $10^{-5}\,kg\cdot m^2$  on the vertical axis (inertial moment) and 0.4s/90° on the horizontal axis (rotation time). Since the resulting intersection point falls within the CRJU1 selection range, CRJU1 may be selected.







## Mini-Rotary Actuator Air Consumption

Air consumption is the volume of air that is expended by the Mini-Rrotary Actuator's reciprocal operation inside the actuator and in the piping between the actuator and the switching valve. It is required for selection of a compressor and for calculation of its running cost.

\* The air consumption (QcR) required for one reciprocation of a single Mini-Rotary Actuator alone is shown in the table below, and can be used to simplify the calculation

#### Formulas

QCR = 
$$2V \times \left( \frac{P + 0.1}{0.1} \right) \times 10^{-3}$$
  
QCP =  $2 \times a \times /x \frac{P}{0.1} \times 10^{-6}$   
QC = QCR + QCP

QCR = Air consumption of Mini-Rotary Actuator [/(ANR)]
QCP = Air consumption of tubing or piping [/(ANR)]
V = Internal volume of Mini-Rotary Actuator [cm³]
P = Operating pressure [MPa]
/ = Length of piping [mm]
a = Internal cross section of piping [mm²]
QC = Air consumption required for one reciprocation of Mini-Rotary Actuator [/(ANR)]

When selecting a compressor, it is necessary to choose one that has sufficient reserve for the total downstream air consumption of all pneumatic actuators. This is affected by factors such as leakage in piping, consumption by drain valves and pilot valves, and reduction of air volume due to temperature drops.

#### Formula

#### $Qc2 = Qc \times n \times Number of actuators \times Reserve factor$

Qc2 = Compressor discharge flow rate

n = Actuator reciprocations per minute

#### Internal cross section of tubing and steel piping

Nominal size	O.D. (mm)	I.D. (mm)	Internal cross section a (mm²)
T□ 0425	4	2.5	4.9
T□ 0604	6	4	12.6
TU 0805	8	5	19.6
T□ 0806	8	6	28.3
1/8B	_	6.5	33.2
T□ 1075	10	7.5	44.2
TU 1208	12	8	50.3
T□ 1209	12	9	63.6
1/4B	_	9.2	66.5
TS 1612	16	12	113
3/8B	_	12.7	127
T□ 1613	16	13	133
1/2B	_	16.1	204
3/4B	_	21.6	366
1B	_	27.6	598

#### **Air Consumption**

Air consumption of rotary actuator: QCR /(ANR)

0:	5	Internal volume			Ope	rating pressure (I	МРа)		
Size	Rotation	(cm <sup>3</sup> )	0.15	0.2	0.3	0.4	0.5	0.6	0.7
05	90°	0.15	0.00074	0.00089	0.0012	0.0015	0.0018	0.0021	0.0024
05	180°	0.31	0.0015	0.0018	0.0025	0.0031	0.0037	0.0043	0.0049
_	90°	0.33	0.0016	0.0020	0.0026	0.0033	0.0039	0.0046	0.0052
1	180°	0.66	0.0033	0.0039	0.0052	0.0065	0.0078	0.0091	0.010





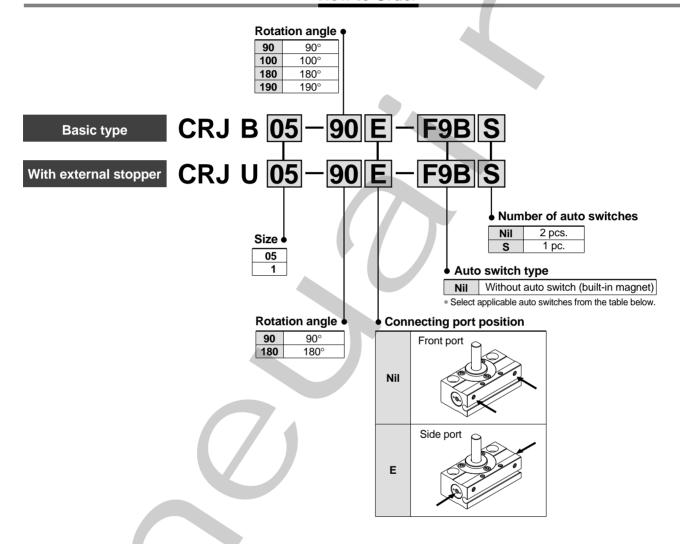


## **Mini-Rotary Actuator**

## Series CRJ



#### **How to Order**



#### Applicable auto switches/\* Refer to pages 7 through 11 for detailed auto switch specifications.

					Lo	ad vo	Itage	Auto swite	ch part no.	Lead w	ire leng	th (m)*							
Ту	pe opecial fullculon		Indicator	Wiring	_	С	AC	Electrical en	ntry direction	0.5	3	5							
	6	entry	light	(output)	U	O	٨٥	Perpendicular	In-line	(Nil)	(Ľ)	5 (Z)							
				3-wire (NPN)				_	F9N	•	•	_							
د ا				3-wire (INPIN)	NPIN)	-		F8N	_	•	•	0							
100			3-wire (PNP)	3-wire (PNP) 2-wire	2 wire (DND)				_	F9P	•	•	_						
								F8P	_	•	•	0							
{	Gre	rommet	Yes		2-wire	24V	12V	_	_	F9B	•	•	_						
1						∠-wire	∠-wire	2-wire	2-wire	2-wire	∠-wire	∠-wire	2-wire				F8B	_	•
7.1	Dia and a dia dia dia dia dia dia dia dia dia			3-wire (NPN)				_	F9NW	•	•	0							
0	Diagnostic indication (2-color indication)			3-wire (PNP)				_	F9PW	•	•	0							
	(2 color indication)		•	2-wire				_	F9BW	•	•	0							

<sup>\*</sup> Lead wire length symbols: 0.5m ..... Nil (Example) F9N 3m ...... L (Example) F9NL 5m ...... Z (Example) F9NWZ



<sup>\*</sup> Auto switches marked "O" are produced upon receipt of order.











Cizo/Turno	0	5		1		
Size/Type	Basic type	With external stopper	Basic type	With external stopper		
Fluid	Air (non-lube)					
Max. operating pressure		0.70	л Ра			
Min. operating pressure	0.15MPa					
Ambient and fluid temperature		0° to 60°C (wit	th no freezing)			
Rotation angle Note)	90 <sup>+8°</sup> <sub>0</sub> , 100 <sup>+10°</sup> <sub>0</sub> 180 <sup>+8°</sup> <sub>0</sub> , 190 <sup>+10°</sup> <sub>0</sub>	90, 180	90 <sup>+8°</sup> <sub>0</sub> , 100 <sup>+10°</sup> <sub>0</sub> 180 <sup>+8°</sup> <sub>0</sub> , 190 <sup>+10°</sup> <sub>0</sub>	90, 180		
Angle adjustment range	_	±5° at each rotation end	_	±5° at each rotation end		
Cylinder bore size	ø6 ø8					
Port size	M3 x 0.5					

Note) If optimum accuracy of the rotation angle is required, select an actuator with external stopper.

#### Allowable Kinetic Energy and Rotation Time Adjustment Range

Size/Type			Allowable kinetic energy (mJ)	Rotation time adjustment range for stable operation (s/90°)
0.5	Basic type	CRJB05	0.25	
05	With external stopper	CRJU05	1.0	0.1 to 0.5
	Basic type	CRJB 1	0.40	0.1 (0 0.5
	With external stopper	CRJU 1	2.0	

#### Weights

Type/Siz	ze	Model	Weight (g) Note)
		CRJB05-90	
	05	CRJB05-100	32
	03	CRJB05-180	20
Danie tuma		CRJB05-190	39
Basic type	1	CRJB 1-90	54
		CRJB 1-100	34
		CRJB 1-180	67
		CRJB 1-190	O1
	05	CRJU05-90	47
With external		CRJU05-180	53
stopper	1	CRJU 1-90	70
	•	CRJU 1-180	81

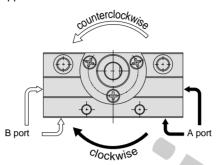
Note) Above values do not include auto switch weights.



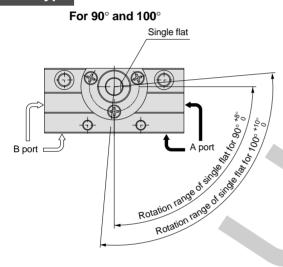


#### **Rotating Direction and Rotation Angle**

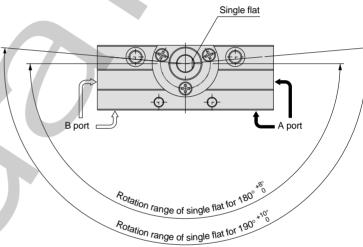
- The shaft turns clockwise when the A port is pressurized, and counterclockwise when the B port is pressurized.
- For actuators with external stopper, the rotation end can be set within the ranges shown in the drawing by adjusting the stopper bolt.



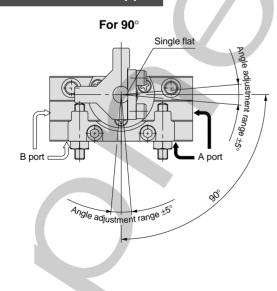
#### Basic type

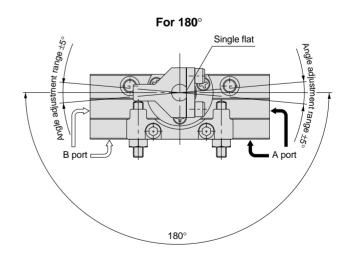


#### For 180° and 190°



#### With external stopper





Note) • The drawings show the rotation range for the shaft's single flat.

 The single flat position in the drawings shows the counterclockwise rotation end when the rotation angle is adjusted to 90° and 180°.



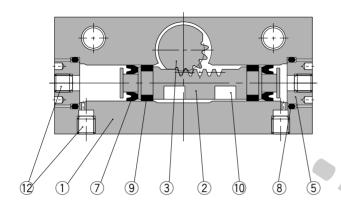


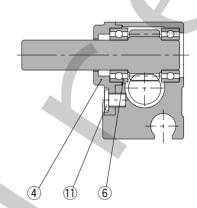
### Series CRJ



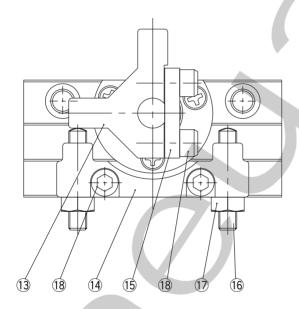
#### Construction

#### Basic type/CRJB





#### With external stopper/CRJU



#### **Parts list**

No.	Description	Material
1	Body	Aluminum alloy
2	Piston	Stainless steel
3	Shaft	Stainless steel
4	Bearing retainer	Aluminum alloy
5	Cover	Aluminum alloy
6	Bearing	Bearing steel
7	Piston seal	NBR
8	O-ring	NBR
9	Wear ring	Resin

No.	Description	Material
10	Magnet	Magnetic material
11	Round head no. 0 Phillips screw	Steel wire
12	Hexagon socket head set screw	Stainless steel
13	Stopper	Chrome molybdenum steel
14	Holder	Aluminum alloy
15	Stopper retainer	Steel
16	Hexagon socket head set screw	Steel wire
17	Hexagon nut	Steel wire
18	Hexagon socket head cap screw	Stainless steel

<sup>\*</sup> The mounting position of hexagon socket head set screws (no. 12) varies depending on the connecting port position.

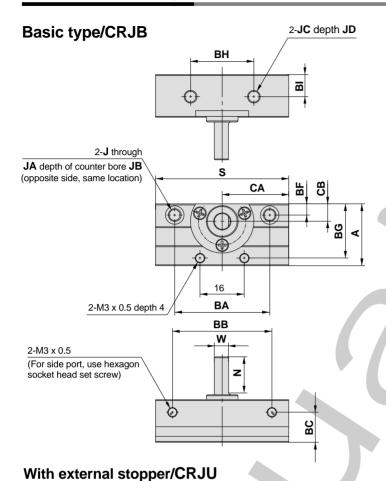




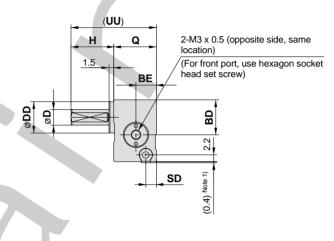


## Mini-Rotary Actuator Series CRJ

#### Dimensions/Size 0.5, 1

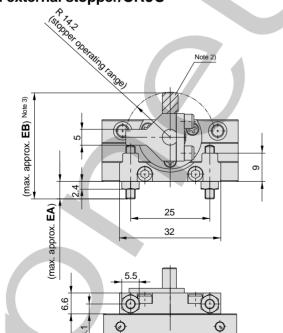


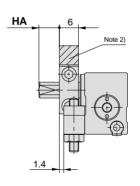
Note 1) This dimension is for the actuator with D-F9 type auto switch (not including the 2-color indication type).



Note 2) For the  $180^{\circ}$  specification, the slated line area do not exist.

Note 3) The maximum dimensions that appear are those measured at the maximum rotation angle settings: 100° and 190°.





(mm)

Size	EA	ЕВ	НА
CRJU05	5.6	33.8	6.5
CRJU 1	5.6	35.8	7.5

(mm)

Size	Rotation angle	Α	ВА	вв	вс	BD	BE	BF	BG	вн	ВІ	СА	СВ	D	DD	J	JA	JB	JC	JD	н	N	Q	s	SD	υυ	w
CRJB05	90°	19.5	30	32.4	9.5	11	6.5	3.5	17 1	20	7	21.5	5.5	506	10h9	M4 v 0 7	5.8	35	M4 x 0.7	5	14 5	12.5	13.5	43	34	28	4.5
CITODOO	180°	15.5	00	43.4	5.5		0.0	0.0	.,	20	,	27	0.0	ogo	10113	WI- X 0.7	0.0	0.0	WI-F X 0.7	Ŭ	14.5	12.5	10.0	54	5.7	20	7.5
CRJB 1	90°	23.5	35	37.4	12.5	14	a	4.5	21 1	22	8.5	24	7.5	606	1/h0	M5 v 0.8	75	45	M5 x 0.8	6	15.5	13.5	16.5	48	5.9	32	5.5
CK3D I	180°	25.5	33	50.4	12.3	14	"	4.5	21.1	22	0.5	30.5	7.5	ogo	14119	WIS X 0.0	7.5	4.5	IVIO X 0.0	"	15.5	13.3	10.5	61	5.5	32	3.3

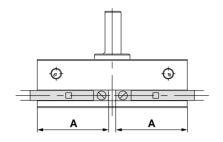




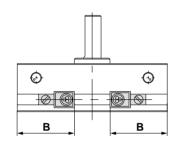




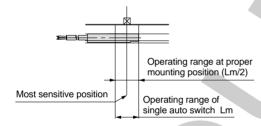
#### **Auto Switch/Proper Mounting Position at Rotation End**



For D-F9



For D-F8



		D-F9 auto switch				D-F8 auto switch			
Size	Rotation	Α		totation nge θm	Actuation range	В	Rotation range θm	Actuation range	
05	90°	20.5		40°	10°	16.5	200	100	
03	180°	23.2		40	10	19.2	20°	10°	
1	90°	22.4		30°	10°	18.4	150	10°	
	180°	25.6		30-	10	21.6	15°		

Rotation range  $\theta m:$  Value of the operating range Lm of a single auto switch converted to an axial rotation range.

Actuation range: Value of auto switch hysteresis converted to an angle.









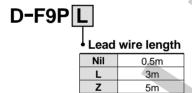
## Series CRJ Auto Switch Common Specifications

#### **Auto Switch Common Specifications**

Туре	Solid state switch		
Operating time	1ms or less		
Impact resistance	1000m/s²		
Insulation resistance	$50 M\Omega$ or more at $500 VDC$ (between lead wire and case)		
Withstand voltage	1000VAC for 1min. (between lead wire and case)		
Ambient temperature	−10° to 60°C		
Enclosure	IEC529 standard IP67 JISC0920 watertight construction		

#### **Lead Wire Lengths**

## Indication of lead wire length (Example)

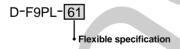


Note 1) Lead wire length Z: Auto switch applicable to 5m length Solid state switches: All models are produced upon receipt of order.

Note 2) The standard lead wire length is 3m for water resistant 2-color indication solid state switches. (0.5m is not available.)

Note 3) For solid state with flexible wire specification, enter "-61" after the lead wire length.

#### (Example)



#### **Lead Wire Color Changes**

Lead wire colors of P/A auto switches have been changed in order to meet standard IEC947-5-2 for production beginning September, 1996 and thereafter, as shown in the tables below.

Take special care regarding wire polarity during the time that the old colors still coexist with the new colors.

#### 2-wire

	Old	New
(+) Output	Red	Brown
(–) Output	Black	Blue

#### 3-wire

	Old	New
(+) Power supply	Red	Brown
GND Power supply	Black	Blue
Output	White	Black

### Solid state with diagnostic output

	Old	New
(+) Power supply	Red	Brown
GND Power supply	Black	Blue
Output	White	Black
Diagnostic output	Yellow	Orange

### Solid state with latch type diagnostic output

	Old	New
(+) Power supply	Red	Brown
GND Power supply	Black	Blue
Output	White	Black
Latch type diagnostic output	Yellow	Orange

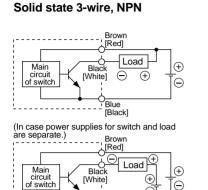




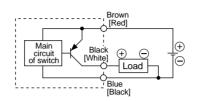


## Series CRJ **Auto Switch Connections and Examples**

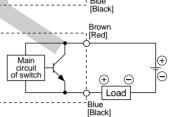
#### **Basic Wiring**



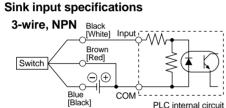
#### Solid state 3-wire, PNP



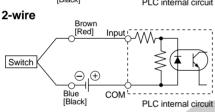
### 2-wire <Solid state> Load Main circuit



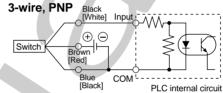
#### **Examples of Connection to PLC**

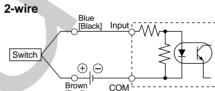


# PLC internal circuit



#### Source input specifications





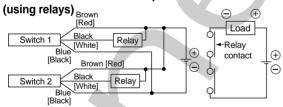
PLC internal circuit

The connection method will vary depending on the applicable PLC input specifications. Connect accordingly.

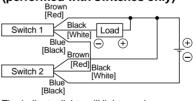
#### Connection Examples for AND (Series) and OR (Parallel)

#### 3-wire

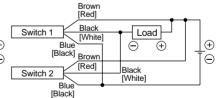
#### AND connection for NPN output



#### **AND connection for NPN output** (performed with switches only)

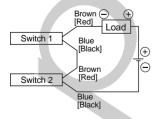


#### **OR connection for NPN output**



The indicator lights will light up when

#### 2-wire, with 2-switch AND connection



When two switches are connected in series, a load may malfunction because the load voltage will decline when in the ON state.

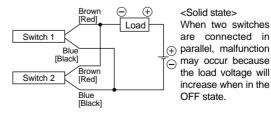
The indicator lights will light up if both of the switches are in the ON state.

Load voltage at ON = 
$$\frac{\text{Power supply}}{\text{voltage}}$$
 -  $\frac{\text{Internal}}{\text{voltage}}$  x 2 pcs.  
= 24V - 4V x 2 pcs.  
= 16V

Example: Power supply is 24VDC.

Internal voltage drop in switch is 4V.

#### both switches are turned ON. 2-wire, with 2-switch OR connection



Load voltage at OFF = Leakage x 2 pcs. x Load impedance = 1mA x 2 pcs. x  $3k\Omega$ = 6 V

Example: Load impedance is  $3k\Omega$ . Leakage current from switch is 1mA.







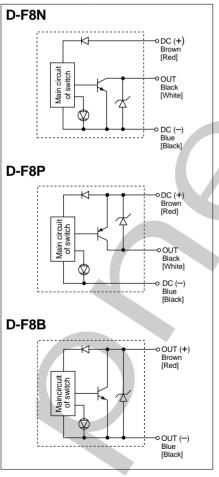
## **Solid State Auto Switches/Direct Mount Type** D-F8N, D-F8P, D-F8B

#### **Grommet**



#### Auto switch internal circuits

Lead wire colors inside [ ] are those prior to conformity with IEC standard.



#### **Auto Switch Specifications**

D-F8□ (with indi	D-F8□ (with indicator light)									
Auto switch part no.	D-F8N	D-F8P	D-F8B							
Electrical entry direction	Perpendicular	Perpendicular	Perpendicular							
Wiring	3-v	vire	2-wire							
Output	NPN type	PNP type	_							
Applicable load	IC circuit, 24V	DC relay, PLC	24VDC relay, PLC							
Power supply voltage	5, 12, 24VDC	_								
Current consumption	10mA	or less	_							
Load voltage	28VDC or less	_	24VDC (10 to 28VDC)							
Load current	40mA or less	80mA or less	2.5 to 40mA							
Internal voltage drop	1.5V or less (0.8V or less at a load current of 10mA)	0.8V or less	4V or less							
Leakage current	100μA or les	0.8mA or less at 24VDC								
Indicator light	R	N								

<sup>•</sup> Lead wires — Heavy duty oil resistant vinyl cord, ø2.7, 0.5m (standard)

D-F8N, D-F8P 0.15mm<sup>2</sup> x 3-wire (Brown, Black, Blue [Red, White, Black])

D-F8B 0.18mm° x 2-wire (Brown, Blue (Red, Black))

• Refer to page 7 for auto switch common specifications and lead wire length options.

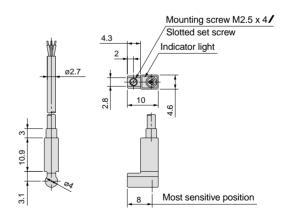
#### **Auto Switch Weights**

Unit: g

Model	D-F8N D-F8P D-F8B					
Lead wire length 0.5m		7				
Lead wire length 3m	32					

#### **Auto Switch Dimensions**

D-F8N, D-F8P, D-F8B









## Solid State Auto Switches/Direct Mount Type D-F9N, D-F9P, D-F9B

#### **Grommet**



#### **Auto Switch Specifications**

D-F9□ (with in	D-F9⊡ (with indicator light)									
Auto switch part no.	D-F9N	D-F9P	D-F9B							
Electrical entry direction	In-line	In-line	In-line							
Wiring	3-v	vire	2-wire							
Output	NPN type	PNP type	_							
Applicable load	IC circuit, R	24VDC relay, PLC								
Power supply voltage	5, 12, 24VDC (4	_								
Current consumption	10mA o	_								
Load voltage	28VDC or less	_	24VDC (10 to 28VDC)							
Load current	40mA or less	80mA or less	5 to 40mA							
Internal voltage drop	1.5V or less (0.8V or less at a load current of 10mA)	0.8V or less	4V or less							
Leakage current	100μA or les	ss at 24VDC	0.8mA or less							
Indicator light	R	N								

• Lead wires — Heavy duty oil resistant vinyl cord, ø2.7, 0.5m (standard)

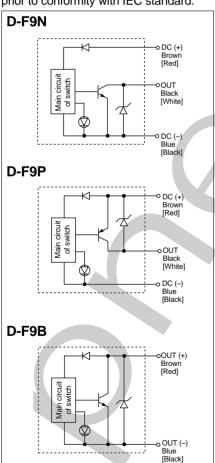
D-F9N, D-F9P 0.15mm² x 3-wire (Brown, Black, Blue [Red, White, Black])

D-F9B 0.18mm² x 2-wire (Brown, Blue [Red, Black])

• Refer to page 7 for auto switch common specifications and lead wire length options.

#### Auto switch internal circuits

Lead wire colors inside [ ] are those prior to conformity with IEC standard.

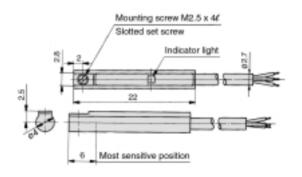


#### **Auto Switch Weights**

			Unit: g
Model	D-F9N	D-F9P	D-F9B
Lead wire length 0.5m	7	7	6
Lead wire length 3m	37	37	31

#### **Auto Switch Dimensions**

D-F9N, D-F9P, D-F9B









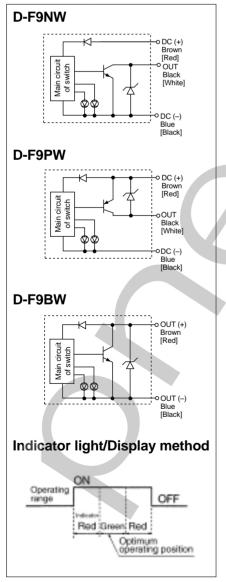
# 2-Color Indication Solid State Auto Switches Direct Mount Type D-F9NW, D-F9PW, D-F9BW

#### **Grommet**



#### Auto switch internal circuits

Lead wire colors inside [ ] are those prior to conformity with IEC standard.



#### **Auto Switch Specifications**

<b>D-F9</b> □ <b>W</b> (with indicator light)							
Auto switch part no.	D-F9NW	D-F9PW	D-F9BW				
Electrical entry direction	In-line	In-line	In-linw				
Wiring	3-1	vire	2-wire				
Output	NPN type	PNP type	_				
Applicable load	IC circuit, R	24VDC relay, PLC					
Power supply voltage	5, 12, 24VDC						
Current consumption	10mA	_					
Load voltage	28VDC or less	_	24VDC (10 to 28VDC)				
Load current	0.4mA or less	80mA or less	5 to 40mA				
Internal voltage drop	1.5V or less (0.8V or less at a load current of 10mA)	0.8V or less	4V or less				
Leakage current	100μA or le	0.8mA or less					
Indicator light	Actuated position Red LED lights up Optimum operating position Green LED lights up						

<sup>•</sup> Lead wires — Heavy duty oil resistant vinyl cord, ø2.7, 0.5m (standard)

0.15mm² x 3-wire (Brown, Black, Blue [Red, White, Black]) 0.18mm² x 2-wire (Brown, Blue [Red, Black]) D-F9NW, D-F9PW

D-F9BW

#### **Auto Switch Weights**

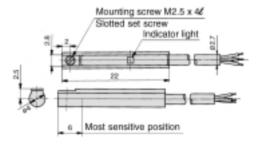
	Offit.	9
D-F9BW		
7		

Linit: a

Model	D-F9NW	D-F9PW	D-F9BW
Lead wire length 0.5m	7	7	7
Lead wire length 3m	34	34	32

#### **Auto Switch Dimensions**

#### D-F9NW, D-F9PW, D-F9BW



<sup>•</sup> Refer to page 7 for auto switch common specifications and lead wire length options.