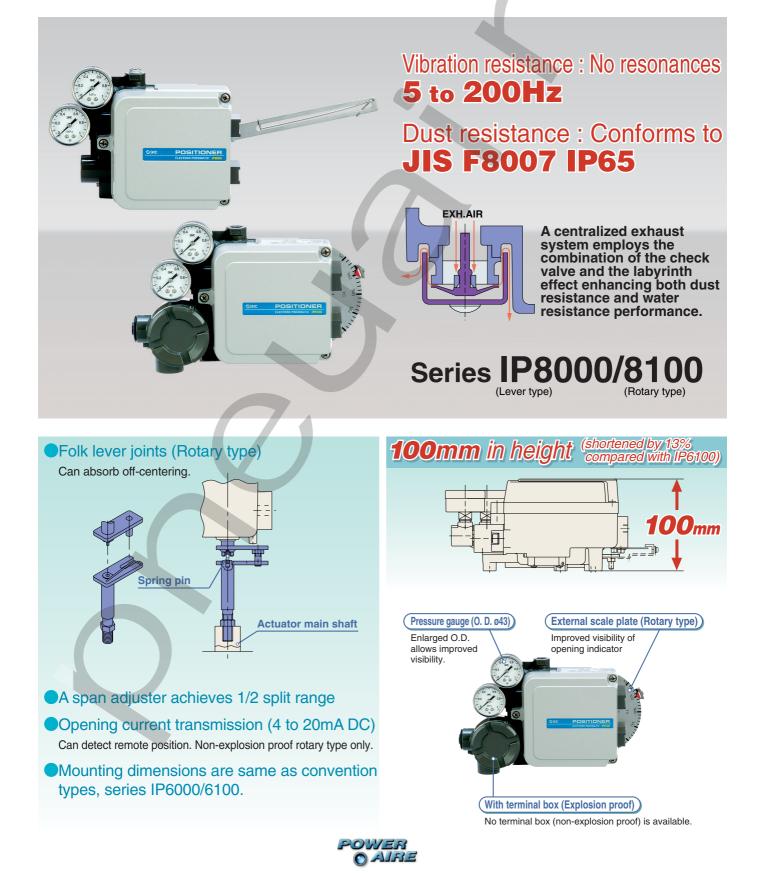




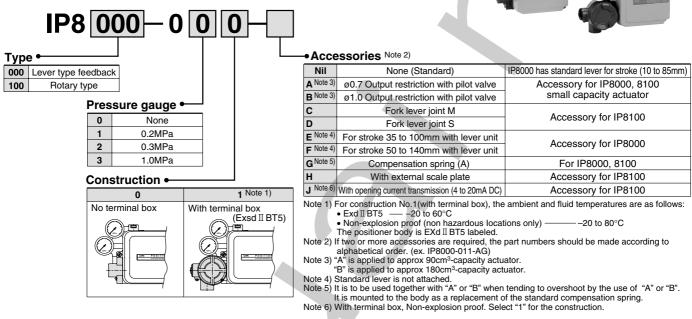
Electro-Pneumatic Positioner





Electro-Pneumatic Positioner Series IP8000/8100

How to Order



Specifications

Туре	IP8000		IP8100	
	Lever type lever feedback		Rotary type cam feedback	
Item	Single action	Double action		
Input current		4 to 20mA	DC Note 1)	
Input resistance		235±15Ω (4 t	o 20mADC)	
Supply air pressure		0.14 to 0		
Standard stroke	10 to 85mm (Deflect	ion angle 10 to 30°)	60 to 100° Note 2)	
Sensitivity	Within 0.1%F.S.		Within 0.5%F.S.	
Linearity	Within ±1%F.S.		Within ±2%F.S.	
Hysteresis	Within 0.75%F.S. Within 1%F.S.		Within 1%F.S.	
Repeatability	Within 0.5%F.S.			
Coefficient of temperature	Within 0.1%F.S. / °C			
Supply pressure fluctuation	Within 0.3%F.S./0.01MPa			
Output flow	80ℓ/min (ANR) or more (SUP = 0.14MPa)			
Cutput now	200ℓ/min (ANR) or more (SUP = 0.4MPa)			
Air consumption	5ℓ/min (ANR) or less (SUP = 0.14MPa)			
All consumption	11ℓ/min (ANR) or less (SUP = 0.4MPa)			
Ambient and fluid	-20 to 80°C (Non-explosion proof)			
temperature	-20 to 60°C (Flame proof and explosion proof)			
Explosion proof	Flame proof and explosion proof construction: Exd II BT5			
construction	(Certificate number: C15916 of Technology Institution of Industrial Safety)			
Air port	Rc 1/4 female			
Electrial connection	G 1/2 female			
Wiring method	Flame proof packing system, Sealant fitting system (explosion-proof)			
	Resin G 1/2 connector (Non-Explosion proof, o		n-Explosion proof, option)	
Exterior covering enclosure	JISF8007, IP65 (conforms to IEC Pub.529)			
Material	Aluminum diecast body / epoxy resin			
Weight	With terminal box 2.6kg (None 2.4kg)			

Explosion Proof

This product has the following approvals. Exd I BT5: Newly established standard based on international (IEC 79)

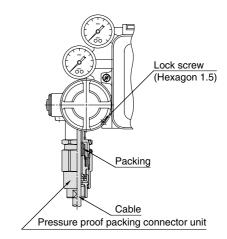
Use as Exd II BT5

(A) Pressure-proof packing.

As shown below in the chart, use "Cable gland" (option). (B) Metal Piping.

Attach the sealant fitting near the cable port.

(For details, refer to "The guideline on electric equipment explosion proof" published by the Technology Institution of Industrial Safety.)



Cable gland with flame proof packing (Option)

		<u> </u>
Part name	Part number	Suited cable outer diameter
Flame proof packing	P368010-32	ø7.0 to ø10.0
connector unit	P368010-33	ø10.1 to ø12.0

Note 1) 1/2 Sprit range (Standard) Note 2) Stroke adjustment: 0 to 60°C, 0 to 100°C





Accessory / Option

Pilot valve with output restriction (IP8000, 8100 type)

In general, mounting on a small-size actuator may cause hunting. For prevention, a pilot valve with a built-in output restriction is available. The restriction is removable.

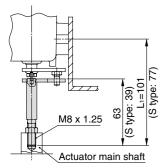
Actuator Capacity	Orifice size	Part number	Pilot unit part number
90cm ³	ø0.7	P36801080	P565010-18
180cm ³	ø1	P36801081	P565010-19

Fork lever joints (IP8100 type)

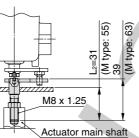
Two types of the fork lever joints are available dependent upon different mounting dimensions.

This is recommended because it can absorb off-centering, compared with direct mounting type.

Part name	Part number	
Fork lever assembly M	P368010-24	
Fork lever assembly S	P368010-25	



lever assembly M

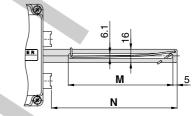


Side mounting with the fork Side mounting with the fork lever assembly S

External feedback lever (IP8000 type)

Different feedback levers are available dependent upon valve strokes. Consult with P/A in case of 10mm or less stroke.

Stroke	Unit number	Size M	Size N
10 to 85mm (Accessory "Nil")	P368010-20	125	150
35 to 100mm (Accessory "E")	P368010-21	110	195
50 to 140mm (Accessory "F")	P368010-22	110	275

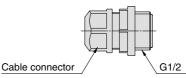


Resin connector (Non-explosion proof specification)

Optional cable connectors are available for different cable sizes. These are not for explosion proof applications.

Cable connector (option)

Part name	Part number	Suited cable outer diameter
Resin-made cable clamp unit (A)	P368010-26	ø7 to ø9
Resin-made cable clamp unit (B)	P368010-27	ø9 to ø11



Exploded View Body cover unit (3) Cover seal Feedback spring Mini-terminal unit (No terminal box) (1) Pilot valve unit Compensation spring Span adjusting unit adiusting ٢ Torque motor unit Feedback shaft assembly Terminal joint unit Feedback (No terminal box) lever unit Body unit **Replacement Parts** Terminal box unit No. Description Part no. Note P565010-7 1 Pilot valve unit 2 Base seal P56501012-3 IP8000/8100 (2) Base seal 3 Cover seal P56501013

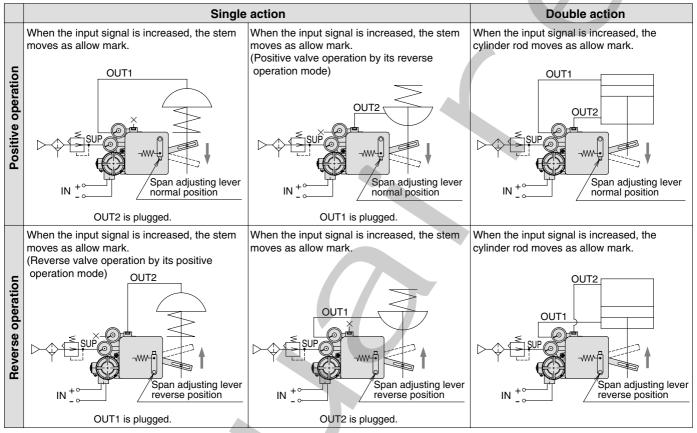




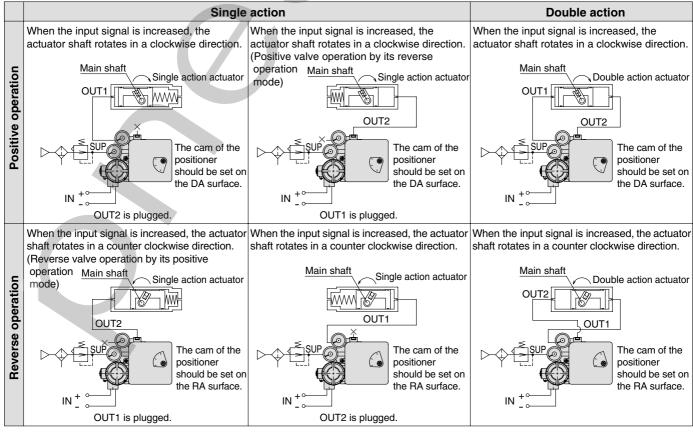
Series **IP8000/8100**



IP8000 / Lever type



IP8100 / Rotary type





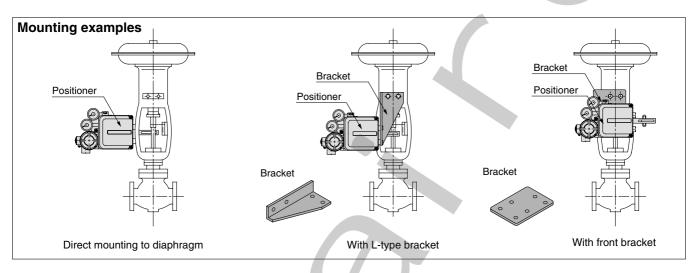


© AIRE Electro-Pneumatic Positioner Series IP8000 / 8100

Installation

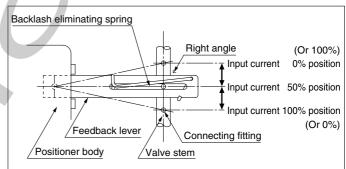
IP8000 type (Lever type lever feedback)

1 The unit should be mounted using bolts firmly fixed through mounting holes on the side or back of the positioner.



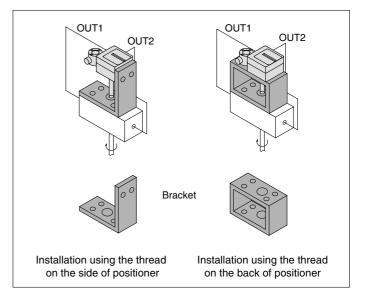
over

2 A connecting fitting or pin to transfer the displacement of valve stem should be mounted at a position so that the feedback lever is at right angles to the valve stem for an input current of 50%. The right figure is the configuration viewed from the front.



IP8100 type (Rotary type cam feedback)

1 The positioner should be mounted so that the feedback shaft is aligned with the shaft of the rotary actuator.







Series **IP8000/8100**

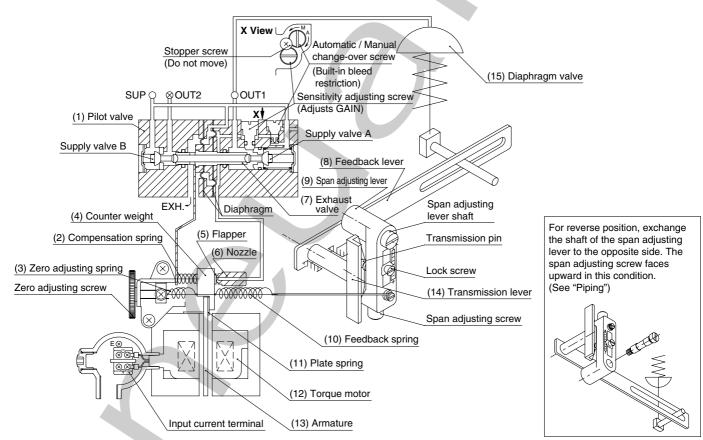


Principle of Operation

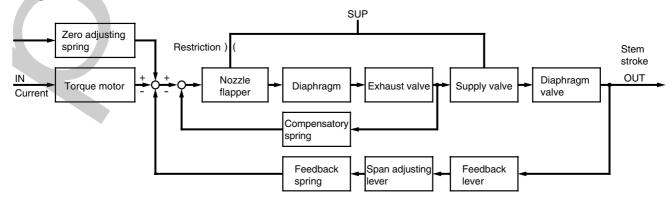
IP8000 / Lever type

When the input current increases, (11) the plate spring of (12) the torque motor will work as a pivot, (13) armature will receive a counter clockwise torque, (4) the counter weight will be pushed to the left, the clearance between (6) the nozzle and (5) the flapper will increase, and the nozzle back pressure will decrease. Consequently, (7) the exhaust valve of (1) the pilot valve moves to the right, the output pressure of OUT1 increases and (15) the diaphragm moves downwards. The motion of (15) the diaphragm acts on (10) the feedback spring through (8) the feedback lever, (14) the transmission lever and (9) the span adjustment lever to rest at the balance position generated by the input current. (2) The compensation spring is for direct feedback of the motion of (7) the exhaust valve to (4) the counter weight to increase the stability of the loop. The zero point should be adjusted by change of (3) the zero adjustment spring tention.

Single action positive operation



Block diagram







Electro-Pneumatic Positioner Series IP8000/8100

For reverse position, set by turning over the cam

and reversing connections

of outlets OUT1 and OUT2.

Feedback

shaft

ovier

IP8100 / Rotary type

When the input current increases, (12) the plate spring of (13) the torque motor will work as a pivot, (14) armature will receive a counter-clockwise torque, (4) the counter weight will be pushed to the left and the clearance between (6) the nozzle and (5) the flapper will increase, and the nozzle back pressure will decrease. Consequently, (7) the exhaust valve of (1) the pilot valve moves to the right, the output pressure of OUT1 increases that of OUT2 decreases and (16) the rotary actuator moves. The motion of (16) the actuator acts on (10) the feedback spring through (11) the feedback shaft, (8) the cam, (9) the span adjustment lever and (15) transmission lever to rest at the balance position generated by the input current. (8) the cam is set on the DA surface and operates positively while (16) the oscillating actuator shaft rotates in a clockwise direction when the input signal is increased. (2) The compensation spring is for direct feedback of the motion of (7) the exhaust valve to (4) the counter weight to increase the stability of the loop. The zero point should be adjusted by change of (3) the zero adjustment spring tension.

Double action positive operation X View Automatic / Manual change-over screw Stopper screw (Do not move) ((Built-in bleed restriction) ΫΟυτι SUP OUT2 Sensitivity adjusting screw (Adjusts GAIN) (1) Pilot valve Supply valve A Supply valve B Ð (7) Exhaust valve EXH. Diaphragm (4) Counter weight (8) Cam (5) Flapper (2) Compensation spring (9) Span adjusting lever (6) Nozzle

(15) Transmission lever Pairing (3) Zero adjusting spring ~ 77 YMM Zero adjusting screw 00000000 (10) Feedback spring (11) Feedback shaft (12) Plate spring `, (16) Oscillating (13) Torque motor actuator Input current terminal (14) Armature Fork joint **Block diagram** SUP Zero adjusting Restriction) spring IN Nozzle Oscillating Torque motor Diaphragm Exhaust valve Supply valve Current flapper actuator



Compensatory spring

Span adjusting

lever

Cam

Feedback

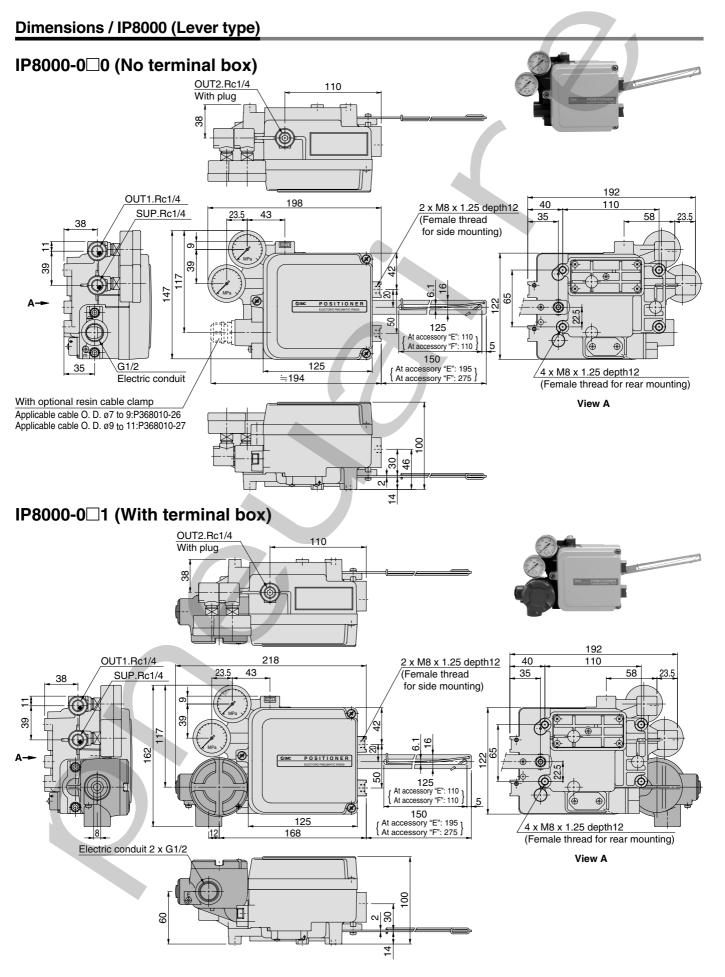
sprina

Angle of rotation OUT



Series IP8000/8100

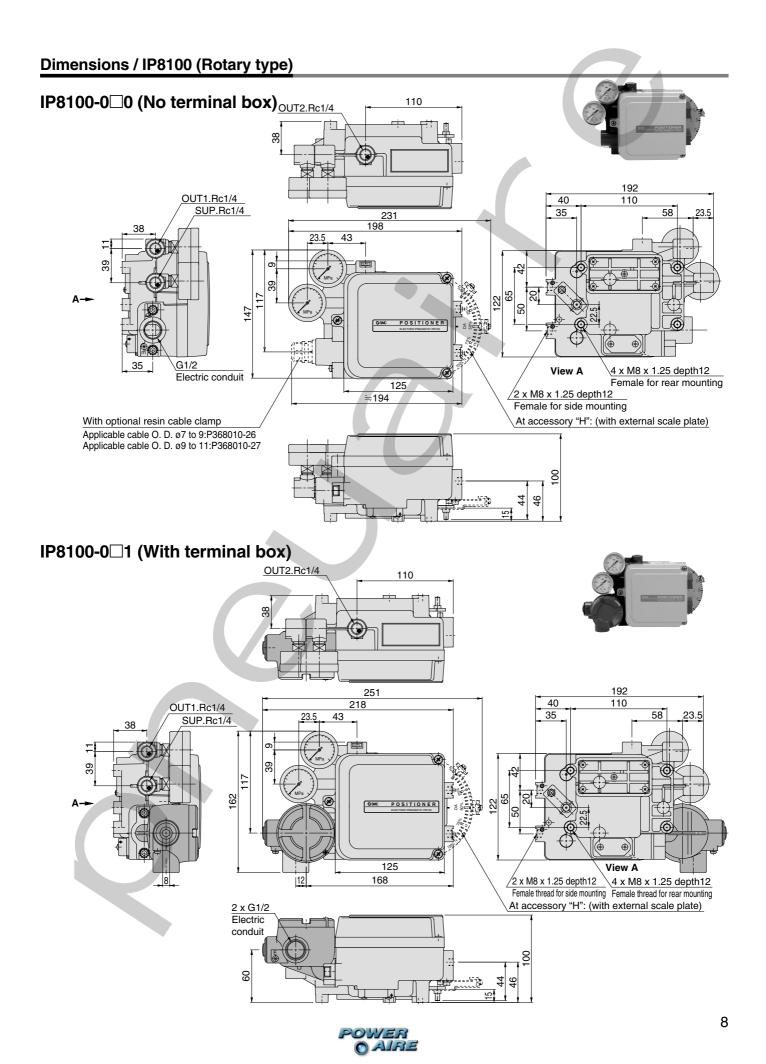








© AIRE Electro-Pneumatic Positioner Series IP8000 / 8100



OWER