

Single Axis Electric Actuator Series **LJ1S** Slider Guide

Series	Motor type	Guide type	Mounting orientation	Model	Lead screw lead	Page
					mm	
LJ1S	Standard motor	Slider guide	Horizontal	LJ1S10	20	88
				LJ1S20	20	90
				LJ1S30	20	92
	Standard motor			LJ1S10	20	94
				LJ1S20	20	96
				LJ1S30	20	98

- Option specifications Page 100
 - Made to Order 101
 - Dust seal specification 116
 - TSUBAKI CABLEVEYOR specification 128
 - Construction 137
 - Mounting 140
- Non-standard Motor Mounting 143
- Deflection Data 145

Part Number Designations

LJ1 S 10 G 1 1 S C - 100 - F W - X10

Guide type

S Slider guide

Series

10	Series 10
20	Series 20
30	Series 30

Motor specification

Nil	Standard motor
G	Matsushita Electric Industrial Co., Ltd.
R	Mitsubishi Electric Corporation
Y	Yaskawa Electric Corporation

Motor output

1	50W
2	100W
3	200W

Power supply voltage

1	100/110VAC 50/60Hz 100/115VAC 50/60Hz
2	200/220VAC 50/60Hz 200/230VAC 50/60Hz
0	Without motor

Stroke

100

Lead screw lead

C 20mm

Lead screw type

S Slide screw

Cable entry direction

F	Axial
R	Right
L	Left
T	Top
B	Bottom

Limit switch

Nil	None
W	B contact specification 2 pcs.

Cable length

2	2m
3	3m
4	4m
5	5m

X10 Non-standard motor

Stroke

100

Lead screw lead

C 20mm

Lead screw type

S Slide screw

Cable entry direction

F	Axial
R	Right
L	Left
T	Top
B	Bottom

Limit switch

Nil	None
W	B contact specification 2 pcs.

Cable length

2	2m
3	3m
4	4m
5	5m

The tables above show the definition for each symbol only and cannot be used for actual model selection.

Standard Motor

Horizontal Mount

Series LJ1S10

Motor Output
50W

Slider
Guide

Slide Screw
∅20mm/20mm lead

How to Order

LJ1H101 **1** **SC** — Stroke — **F** **2**

Power supply voltage

1	100/110VAC (50/60Hz)
2	200/220VAC (50/60Hz)

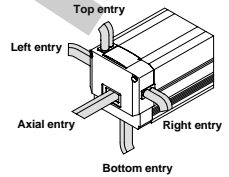
Cable entry direction

F	Axial
R	Right
L	Left
T	Top
B	Bottom

Cable length

2	2m
3	3m
4	4m
5	5m

Cable entry direction



Specifications

Standard stroke		mm	100	200	300	400	500	600	700	800	900	1000
Performance	Body weight	kg	5.4	6.1	6.9	7.7	8.5	9.3	10.0	10.8	11.6	12.4
	Operating temperature range	°C	5 to 40 (with no condensation)									
	Work load	kg	5									
	Rated thrust	N	24									
	Maximum speed	mm/s	300									
	Positioning repeatability	mm	±0.1									
Main parts	Motor	AC servomotor (50W)										
	Encoder	Incremental system										
	Lead screw	Slide screw ∅20mm, 20mm lead										
	Guide	Slider guide										
	Motor/Screw connection	With coupling										
Controller	Model	LC1-1B1S□-□ (Refer to page 185 for details.)										

Intermediate strokes

For manufacture of strokes other than the standard strokes above, add "-X2" at the end of the part number.
Applicable strokes: 150, 250, 350, 450, 550, 650, 750, 850, 950
Example) LJ1S1011SC-150-F2-X2

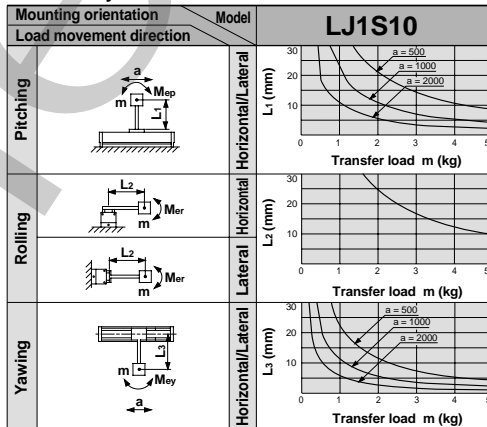
Allowable Moment (N·m)

Allowable static moment

Pitching	1.3
Rolling	1.5
Yawing	0.7

- m : Transfer load (kg)
- a : Work piece acceleration (mm/s²)
- Me: Dynamic moment
- L : Overhang to work piece center of gravity (mm)

Allowable dynamic moment

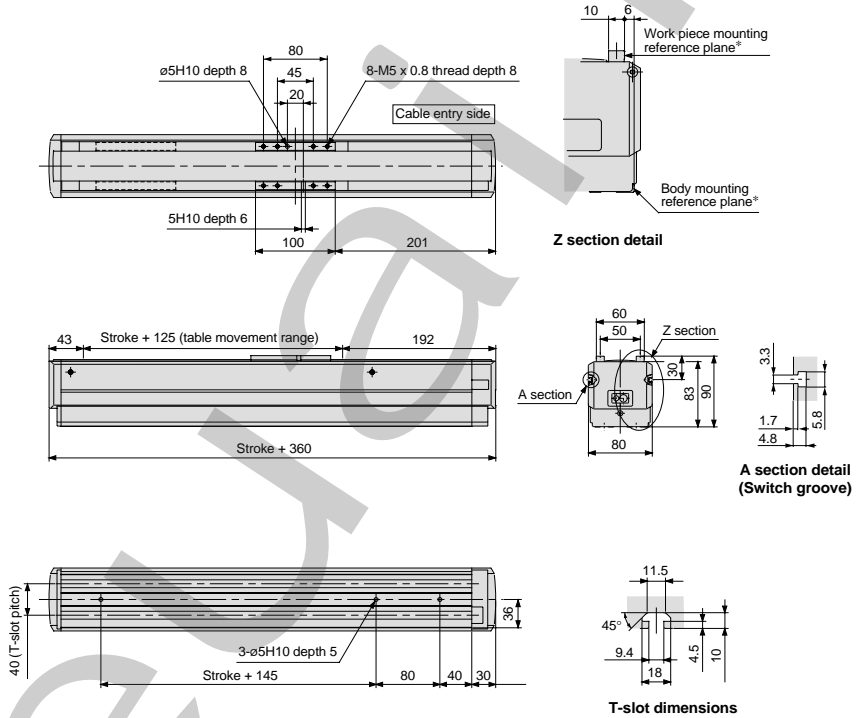


Refer to page 145 for deflection data.

Standard Motor/Horizontal Mount Specification **Series LJ1S10**

Dimensions/LJ1S10□SC

Scale: 15%

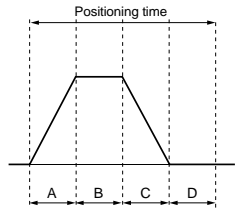


* The body mounting reference plane and work piece mounting reference plane should be used as standards when mounting onto equipment. Refer to pages starting with 140 for mounting.

Positioning Time Guide

Positioning distance (mm)		Positioning time (sec.)				
		1	10	100	500	1000
Speed (mm/s)	10	0.5	1.4	10.4	50.4	100.4
	100	0.4	0.5	1.4	5.4	10.4
	150	0.4	0.5	1.1	3.8	7.1
	300	0.4	0.5	0.8	2.2	3.8

* Values will vary slightly depending on the operating conditions.



A: Acceleration time
 B: Constant velocity time
 C: Deceleration time
 D: Resting time (0.1sec.)
 Maximum acceleration: 2000mm/s²

Standard Motor

Horizontal Mount

Series LJ1S20

Motor Output

100W

Slider Guide

Slide Screw

∅20mm/20mm lead

How to Order

LJ1S202 **1** **SC** — Stroke — **F** **2**

Power supply voltage

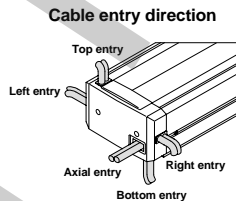
1	100/110VAC (50/60Hz)
2	200/220VAC (50/60Hz)

Cable entry direction

F	Axial
R	Right
L	Left
T	Top
B	Bottom

Cable length

2	2m
3	3m
4	4m
5	5m



Specifications

	Standard stroke	mm	100	200	300	400	500	600	700	800	900	1000	1200		
Performance	Body weight	kg	6.8	7.9	9.0	10.1	11.1	12.2	13.3	14.3	15.4	16.4	18.6		
	Operating temperature range	°C	5 to 40 (with no condensation)												
	Work load	kg									10				
	Rated thrust	N									50				
	Maximum speed	mm/s									300				
Main parts	Motor		AC servomotor (100W)												
	Encoder		Incremental system												
	Lead screw		Slide screw ∅20mm, 20mm lead												
	Guide		Slider guide												
	Motor/Screw connection		With coupling												
Controller	Model		LC1-1B2S□□□ (Refer to page 185 for details.)												

Intermediate strokes

For manufacture of strokes other than the standard strokes above, add "-X2" at the end of the part number.
 Applicable strokes: 150, 250, 350, 450, 550, 650, 750, 850, 950, 1050
 Example) LJ1S2021SC-150-F2-X2

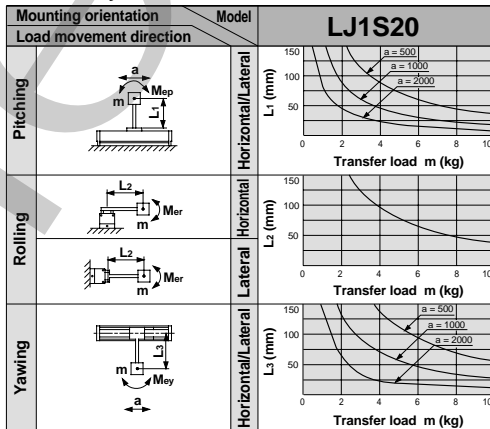
Allowable Moment (N·m)

Allowable static moment

Pitching	5.5
Rolling	6.0
Yawing	8.5

m : Transfer load (kg)
 a : Work piece acceleration (mm/s²)
 Me : Dynamic moment
 L : Overhang to work piece center of gravity (mm)

Allowable dynamic moment



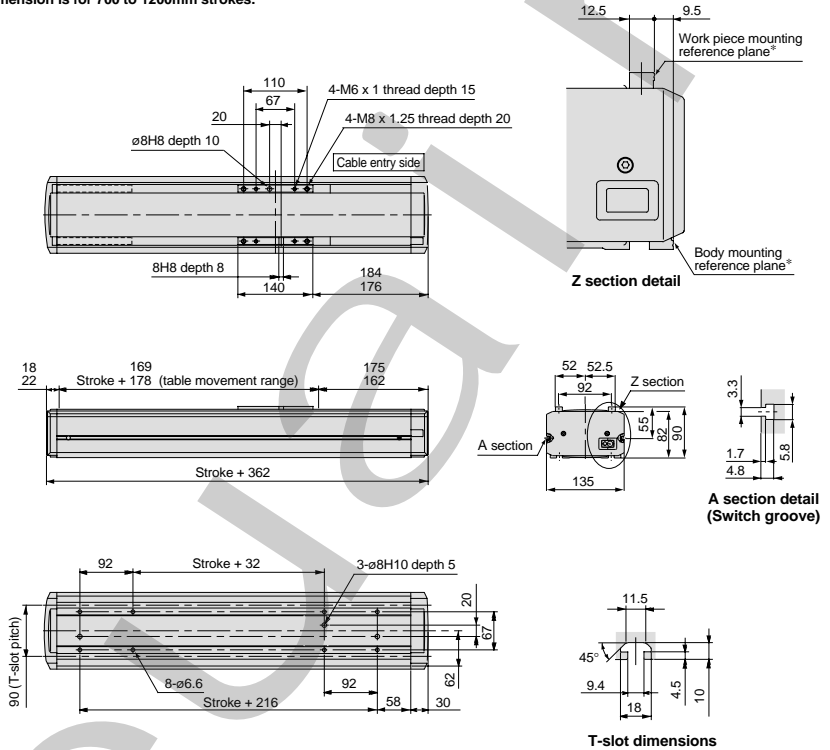
Refer to page 145 for deflection data.

Standard Motor/Horizontal Mount Specification **Series LJ1S20**

Dimensions/LJ1S20□SC

When two dimensions are shown, the top dimension is for 100 to 600mm strokes, and the bottom dimension is for 700 to 1200mm strokes.

Scale: 10%

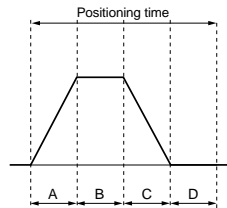


* The body mounting reference plane and work piece mounting reference plane should be used as standards when mounting onto equipment. Refer to pages starting with 140 for mounting.

Positioning Time Guide

Positioning distance (mm)		Positioning time (sec.)				
		1	10	100	600	1200
Speed (mm/s)	10	0.6	1.5	10.5	60.5	120.5
	100	0.5	0.6	1.5	6.5	12.5
	150	0.5	0.6	1.2	4.5	8.5
	300	0.5	0.6	0.9	2.6	4.6

* Values will vary slightly depending on the operating conditions.



A: Acceleration time
B: Constant velocity time
C: Deceleration time
D: Resting time (0.4sec.)
Maximum acceleration: 2000mm/s²

Standard Motor**Horizontal Mount****Series LJ1S30**

Motor Output

200W

Slider

Guide

Rolled Ball Screw

ø25mm/20mm lead

How to Order**LJ1S303 1 SC Stroke F 2**

Power supply voltage

1	100/110VAC (50/60Hz)
2	200/220VAC (50/60Hz)

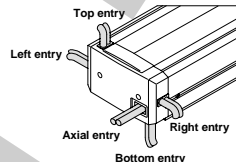
Cable entry direction

F	Axial
R	Right
L	Left
T	Top
B	Bottom

Cable length

2	2m
3	3m
4	4m
5	5m

Cable entry direction

**Specifications**

	Standard stroke	mm	200	300	400	500	600	800	1000	1200	1500
Performance	Body weight	kg	14.4	16.2	18.0	19.8	21.5	25.7	29.7	33.3	38.7
	Operating temperature range	°C	5 to 40 (with no condensation)								
	Work load	kg	20								
	Rated thrust	N	50								
	Maximum speed	mm/s	300								
Main parts	Positioning repeatability	mm	±0.1								
	Motor		AC servomotor (200W)								
	Encoder		Incremental system								
	Lead screw		Slide screw ø25mm, 20mm lead								
	Guide		Slider guide								
Controller	Motor/Screw connection		With coupling								
	Model		LC1-1B3S□-□□ (Refer to page 185 for details.)								

Intermediate strokes

For manufacture of strokes other than the standard strokes above, add "-X2" at the end of the part number.

Applicable strokes: 250, 350, 450, 550, 650, 700, 750, 850, 900, 950, 1050, 1100, 1150, 1250, 1300, 1350, 1400, 1450

Example) LJ1S3031SC-250-F2-X2

Allowable Moment (N·m)**Allowable static moment**

Pitching	26.6
Rolling	40.2
Yawing	25.8

m : Transfer load (kg)

a : Work piece acceleration (mm/s²)

Me: Dynamic moment

L : Overhang to work piece center of gravity (mm)

Allowable dynamic moment

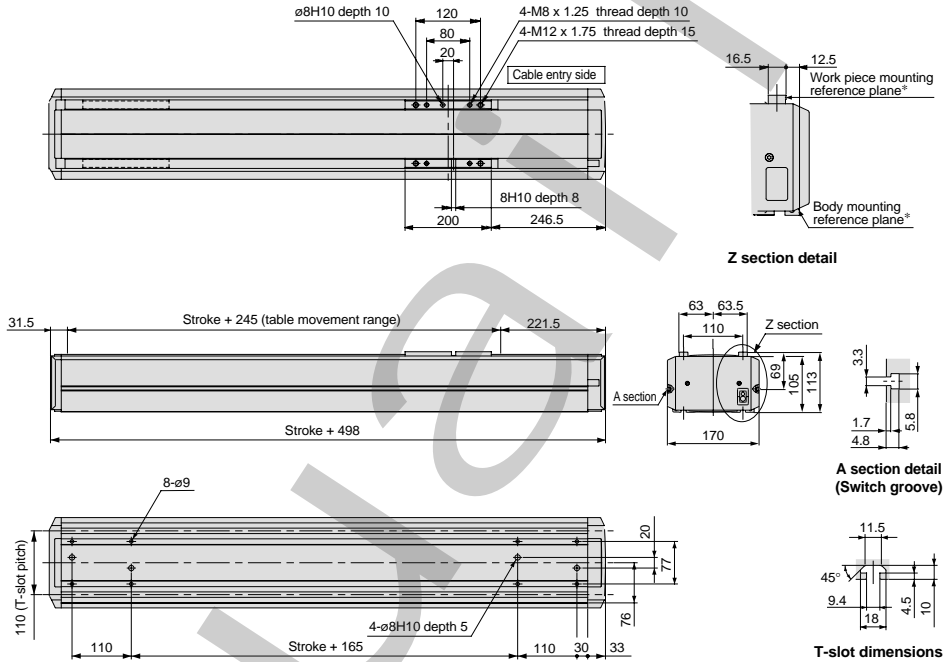
Mounting orientation		Model
Load movement direction		LJ1S30
Pitching	Horizontal/Lateral	
	Rolling	
Rolling	Horizontal	
	Lateral	
Yawing	Horizontal/Lateral	
	Rolling	

Refer to page 145 for deflection data.

Standard Motor/Horizontal Mount Specification **Series LJ1S30**

Dimensions/LJ1S303□SC

Scale: 10%

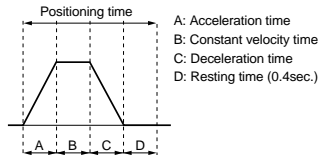


* The body mounting reference plane and work piece mounting reference plane should be used as standards when mounting onto equipment. Refer to pages starting with 140 for mounting.

Positioning Time Guide

		Positioning time (sec.)				
Positioning distance (mm)		1	10	100	750	1500
Speed (mm/s)	10	0.5	2.1	11.1	76.1	151.1
	100	1.1	1.2	2.1	8.6	16.1
	500	1.1	1.2	1.6	4.2	7.2
	1000	1.1	1.2	1.5	2.8	4.3

* Values will vary slightly depending on the operating conditions.



How to Order

LJ1S10 **G** 1 1 **SC** — Stroke — **F** **W** — X10

Motor specification

G	Matsushita Electric Industrial Co., Ltd.
R	Mitsubishi Electric Corporation
Y	Yaskawa Electric Corporation

Power supply voltage

1	100/115VAC (50/60Hz)
2	200/230VAC (50/60Hz)
0	Without motor

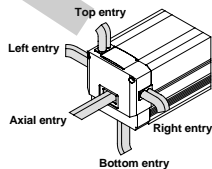
Cable entry direction

F	Axial
R	Right
L	Left
T	Top
B	Bottom

Switch

Nil	None
W	N.C. (B contact) 2 pcs.

Cable entry direction



Specifications

	Standard stroke	mm	100	200	300	400	500	600	700	800	900	1000		
Performance	Body weight (without motor)	kg	5.0	5.7	6.5	7.3	8.1	8.9	9.6	10.4	11.2	12.0		
	Operating temperature range	°C	5 to 40 (with no condensation)											
	Work load	kg									5			
	Maximum speed	mm/s									300			
Main parts	Positioning repeatability	mm	±0.1											
	Motor		AC servomotor (50W)											
	Encoder		Incremental system											
	Lead screw		Slide screw Ø20mm, 20mm lead											
	Guide		Slider guide											
	Motor/Screw connection		With coupling											
Switch	Model		D-Y7GL											
	Specifications		Power supply voltage: 4.5 to 28VDC, Current consumption: 10mA or less Control output: Open collector, Load current: 40mA or less, Internal voltage drop: 1.5V or less											

Intermediate strokes

Strokes other than the standard strokes above are available by special order. Consult P/A.

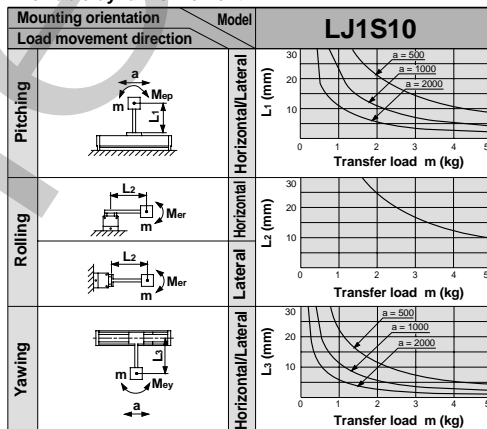
Allowable Moment (N·m)

Allowable static moment

Pitching	1.3
Rolling	1.5
Yawing	0.7

m : Transfer load (kg)
a : Work piece acceleration (mm/s²)
Me: Dynamic moment
L : Overhang to work piece center of gravity (mm)

Allowable dynamic moment

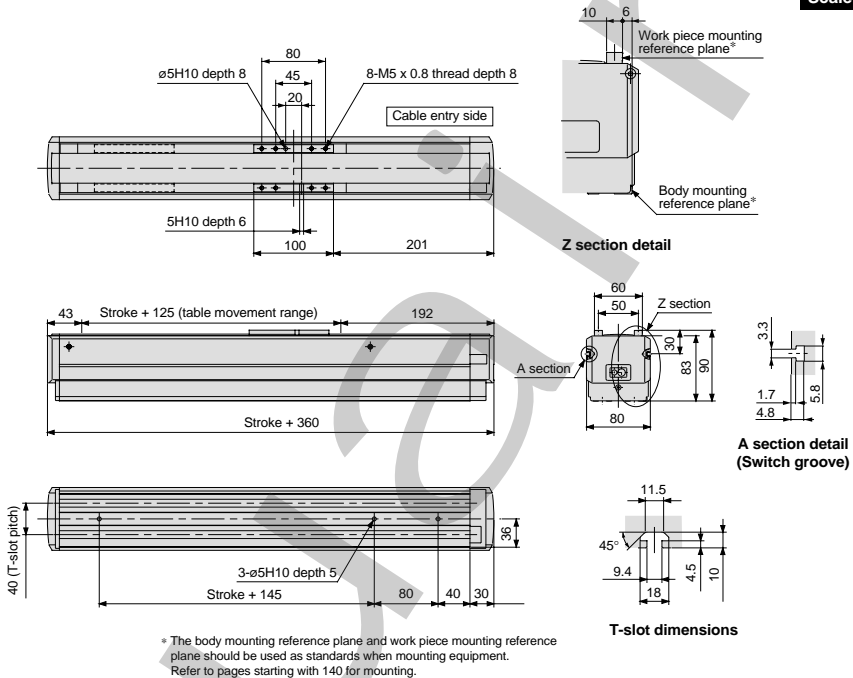


Refer to page 145 for deflection data.

Non-standard Motor/Horizontal Mount Specification **Series LJ1S10**

Dimensions/LJ1S10□1□SC(X10)

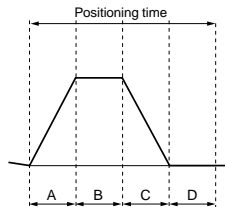
Scale: 15%



Positioning Time Guide

Positioning distance (mm)		Positioning time (sec.)				
		1	10	100	500	1000
Speed (mm/s)	10	0.5	1.4	10.4	50.4	100.4
	100	0.4	0.5	1.4	5.4	10.4
	150	0.4	0.5	1.1	3.8	7.1
	300	0.4	0.5	0.8	2.2	3.8

* Values will vary slightly depending on the operating conditions.



A: Acceleration time
 B: Constant velocity time
 C: Deceleration time
 D: Resting time (0.1sec.)*
 Maximum acceleration: 2000mm/s²
 * The value is a guide when SMC's series LC1 controller is used and may vary depending on the driver capacity.

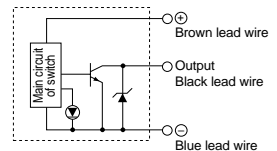
Non-standard Motors: The following motors will be mounted when a motor mounted type is specified.

	Motor output (W)	Power supply voltage (VAC)	Motor model	Compatible driver model
Matsushita Electric Industrial Co., Ltd.	50	100/115	MSM5AZP1A	MSD5A1P1E
		200/230		MSD5A3P1E
Mitsubishi Electric Corporation	50	100/115	HC-PQ053	MR-C10A1
		200/230		MR-C10A
Yaskawa Electric Corporation	50	100/115	SGME-A5BF12	SGDE-A5BP
		200/230	SGME-A5AF12	SGDE-A5AP

* For motor mounting dimensions, refer to the dimensions for series LJ1S10 on page 143 as a reference for mounting and design.
 * Refer to pages starting with 205 for driver dimensions, etc. Furthermore, for detailed specifications, etc., contact each motor manufacturer.
 * For a non-standard motor specification, when the motor is mounted before shipping, the driver is included but the cable that connects the motor and driver is optional. Refer to page 100 for part numbers.

Switch Internal Circuit

D-Y7GL



How to Order

LJ1S20 **G** 2 **1** **SC** — Stroke — **F** **W** — X10

Motor specification

G	Matsushita Electric Industrial Co., Ltd.
R	Mitsubishi Electric Corporation
Y	Yaskawa Electric Corporation

Power supply voltage

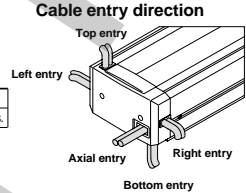
1	100/115VAC (50/60Hz)
2	200/230VAC (50/60Hz)
0	Without motor

Cable entry direction

F	Axial
R	Right
L	Left
T	Top
B	Bottom

Switch

Nil	None
W	N.C. (B contact) 2 pcs.



Specifications

Standard stroke		mm	100	200	300	400	500	600	700	800	900	1000	1200
Performance	Body weight (without motor)	kg	6.3	7.4	8.5	9.6	10.6	11.7	12.8	13.8	14.9	15.9	18.1
	Operating temperature range	°C	5 to 40 (with no condensation)										
	Work load	kg	10										
	Maximum speed	mm/s	300										
	Positioning repeatability	mm	±0.1										
Main parts	Motor	AC servomotor (100W)											
	Encoder	Incremental system											
	Lead screw	Slide screw ∅20mm, 20mm lead											
	Guide	Slider guide											
	Motor/Screw connection	With coupling											
Switch	Model	D-Y7GL											
	Specifications	Power supply voltage: 4.5 to 28VDC, Current consumption: 10mA or less Control output: Open collector, Load current: 40mA or less, Internal voltage drop: 1.5V or less											

Immediate strokes

Strokes other than the standard strokes above are available by special order. Consult P/A.

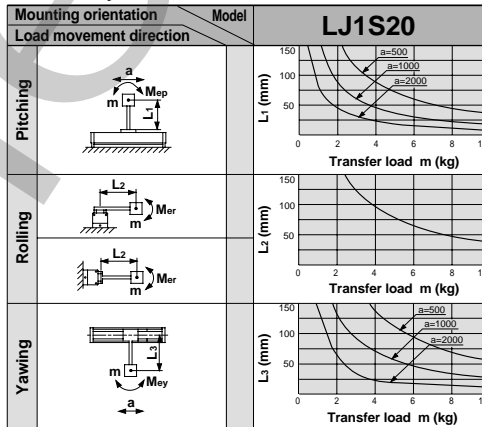
Allowable Moment (N·m)

Allowable static moment

Pitching	5.5
Rolling	6.0
Yawing	8.5

m : Transfer load (kg)
a : Work piece acceleration (mm/s²)
Me : Dynamic moment
L : Overhang to work piece center of gravity (mm)

Allowable dynamic moment



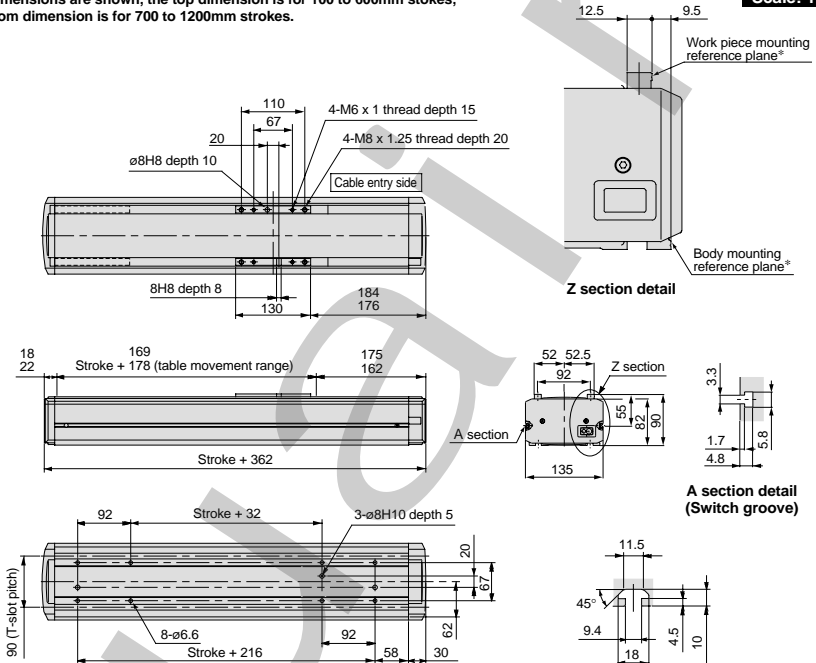
Refer to page 145 for deflection data.

Non-standard Motor/Horizontal Mount Specification **Series LJ1S20**

Dimensions/LJ1S20□□SC(X10)

When two dimensions are shown, the top dimension is for 100 to 600mm strokes, and the bottom dimension is for 700 to 1200mm strokes.

Scale: 10%

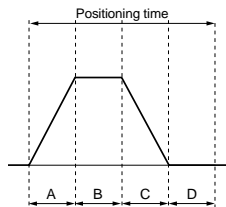


* The body mounting reference plane and work piece mounting reference plane should be used as standards when mounting onto equipment. Refer to pages starting with 140 for mounting.

Positioning Time Guide

Positioning distance (mm)	Positioning time (sec.)					
	1	10	100	500	1000	
Speed (mm/s)	10	0.6	1.5	10.5	50.5	120.5
	100	0.5	0.6	1.5	6.5	12.5
	150	0.5	0.6	1.2	4.5	8.5
	300	0.5	0.6	0.9	2.6	4.6

* Values will vary slightly depending on the operating conditions.



A: Acceleration time
 B: Constant velocity time
 C: Deceleration time
 D: Resting time (0.4sec.)*
 Maximum acceleration: 2000mm/s²

* The value is a guide when SMC's series LC1 controller is used and may vary depending on the driver capacity.

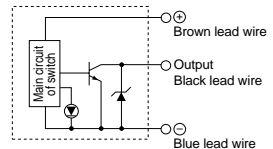
Non-standard Motors: The following motors will be mounted when a motor mounted type is specified.

	Motor output (W)	Power supply voltage (VAC)	Motor model	Compatible driver model
Matsushita Electric Industrial Co., Ltd.	100	100/115	MSM011P1A	MSD011P1E
		200/230	MSM012P1A	MSD013P1E
Mitsubishi Electric Corporation	100	100/115	HC-PQ13	MR-C10A1
		200/230		MR-C10A
Yaskawa Electric Corporation	100	100/115	SGME-01BF12	SGDE-01BP
		200/230	SGME-01AF12	SGDE-01AP

- * For motor mounting dimensions, refer to the dimensions for series LJ1S20 on page 143 as a reference for mounting and design.
- * Refer to pages starting with 205 for driver dimensions, etc. Furthermore, for detailed specifications, etc., contact each motor manufacturer.
- * For a non-standard motor specification, when the motor is mounted before shipping, the driver is included but the cable that connects the motor and driver is optional. Refer to page 100 for part numbers.

Switch Internal Circuit

D-Y7GL



How to Order

LJ1S30 **G** 3 **1** **SC** — Stroke — **F** **W** — X10

Motor specification

G	Matsushita Electric Industrial Co., Ltd.
R	Mitsubishi Electric Corporation
Y	Yaskawa Electric Corporation

Power supply voltage

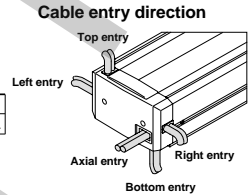
1	100/115VAC (50/60Hz)
2	200/230VAC (50/60Hz)
0	Without motor

Cable entry direction

F	Axial
R	Right
L	Left
T	Top
B	Bottom

Switch

Nil	None
W	N.C. (B contact) 2 pcs.



Specifications

Standard stroke		mm	200	300	400	500	600	800	1000	1200	1500
Performance	Body weight (without motor)	kg	13.3	15.1	16.9	18.7	20.4	24.6	28.6	32.2	37.6
	Operating temperature range	°C	5 to 40 (with no condensation)								
	Work load	kg	20								
	Maximum speed	mm/s	300								
	Positioning repeatability	mm	±0.1								
Main parts	Motor	AC servomotor (200W)									
	Encoder	Incremental system									
	Lead screw	Slide screw ø25mm, 20mm lead									
	Guide	Slider guide									
	Motor/Screw connection	With coupling									
Switch	Model	D-Y7GL									
	Specifications	Power supply voltage: 4.5 to 28VDC, Current consumption: 10mA or less Control output: Open collector, Load current: 40mA or less, Internal voltage drop: 1.5V or less									

Immediate strokes

Strokes other than the standard strokes above are available by special order. Consult P/A.

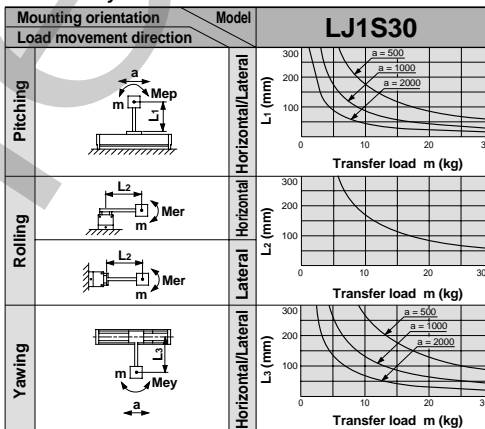
Allowable Moment (N·m)

Allowable static moment

Pitching	26.6
Rolling	40.2
Yawing	25.8

m : Transfer load (kg)
a : Work piece acceleration (mm/s²)
Me: Dynamic moment
L : Overhang to work piece center of gravity (mm)

Allowable dynamic moment

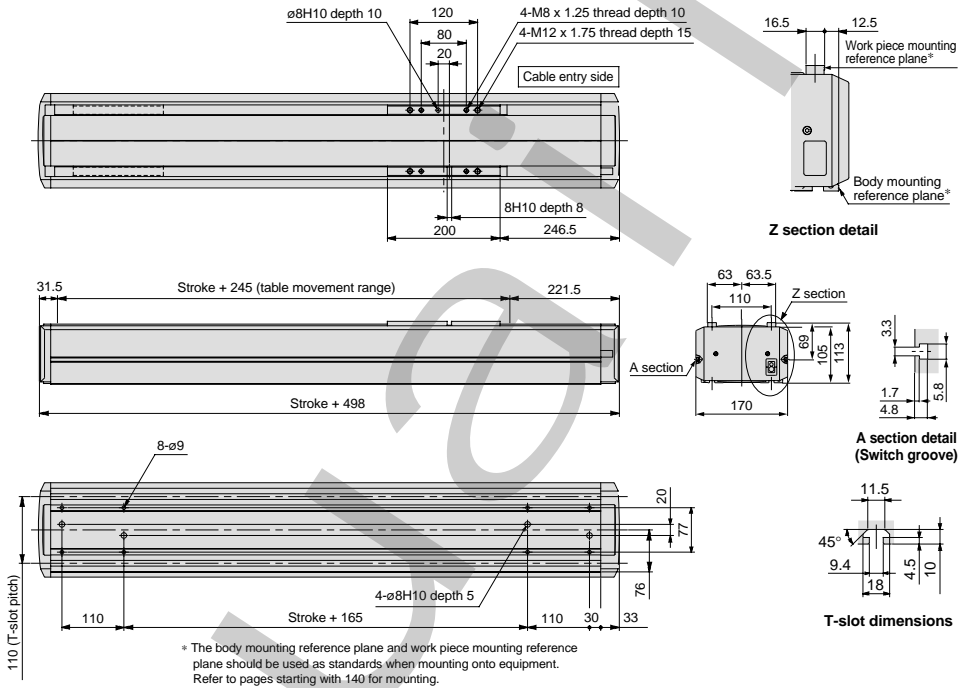


Refer to page 145 for deflection data.

Non-standard Motor/Horizontal Mount Specification **Series LJ1S30**

Dimensions/LJ1S30□3□SC(X10)

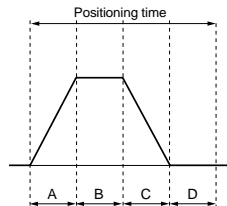
Scale: 10%



Positioning Time Guide

Positioning distance (mm)	Positioning time (sec.)					
	1	10	100	750	1500	
Speed (mm/s)	10	0.5	2.1	11.1	76.1	151.1
	100	1.1	1.2	2.1	8.6	16.1
	250	1.1	1.2	1.6	4.2	7.2
	500	1.1	1.2	1.5	2.8	4.3

* Values will vary slightly depending on the operating conditions.



A: Acceleration time
 B: Constant velocity time
 C: Deceleration time
 D: Resting time (0.4sec.)*
 Maximum acceleration: 2000mm/s²
 * The value is a guide when SMC's series LCI controller is used and may vary depending on the driver capacity.

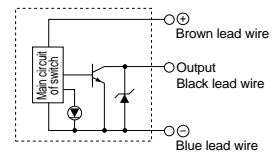
Non-standard Motors: The following motors will be mounted when a motor mounted type is specified.

	Motor output (W)	Power supply voltage (VAC)	Motor model	Compatible driver model
Matsushita Electric Industrial Co., Ltd.	200	100/115	MSM021P1A	MSD021P1E
		200/230	MSM022P1A	MSD023P1E
Mitsubishi Electric Corporation	200	100/115	HC-PQ23	MR-C20A1
		200/230		MR-C20A
Yaskawa Electric Corporation	200	100/115	SGME-02BF12	SGDE-02BP
		200/230	SGME-02AF12	SGDE-02AP

* For motor mounting dimensions, refer to the dimensions for series LJ1S30 on page 143 as a reference for mounting and design.
 * Refer to pages starting with 205 for driver dimensions, etc. Furthermore, for detailed specifications, etc., contact each motor manufacturer.
 * For a non-standard motor specification, when the motor is mounted before shipping, the driver is included but the cable that connects the motor and driver is optional. Refer to page 100 for part numbers.

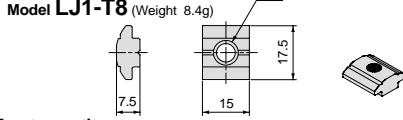
Switch Internal Circuit

D-Y7GL



T-nuts for mounting electric actuators

Use T-nuts for T-slot mounting of an actuator. When mounting by means of T-nuts alone, the quantity of nuts indicated below should be used as a minimum.



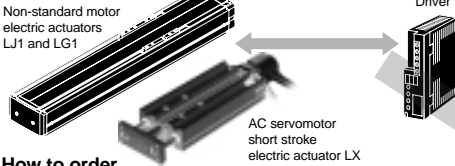
T-nut quantity

Model	Quantity
LJ1¹10	200mm stroke or less: 6 pcs.
	300mm stroke or more: 8 pcs.
LJ1¹20	8 pcs.
LJ1¹30	8 pcs.

* Only series LJ1¹10 has the T-nuts built into the body.

Non-standard Motor Cables

These are cables for connecting non-standard motors and drivers. Cable lengths other than those shown below should be arranged by the customer.



How to order

LJ1 - 1 - G 05 B

Compatible model

G	Matsushita Electric Industrial Co., Ltd.
R	Mitsubishi Electric Corporation
Y	Yaskawa Electric Corporation

Brake

Nil	Without brake
B	With brake

Cable length

05	5m
-----------	----

Applicable cables

LJ1 (non-standard motor), LXP/LXS (AC servomotor)

Model	Manufacturer part no.
LJ1-1-G05¹	MFMA0050AEB (for motor)
	MFCA0050EAB (for encoder)
LJ1-1-G05B	MFCA0050FAB (for motor)
	MFMA0050AEB (for encoder)
	MFMCB0050CET (for brake)
LJ1-1-R05	(for motor) ²
	MR-JCCBL5M (for encoder)
LJ1-1-Y05³	DP9320081-2 (for motor)
	DP9320089-2 (for encoder)
LJ1-1-Y05B	DP9320083-2 (for motor/brake)
	DP9320089-2 (for encoder)

LXF (AC servomotor by Mitsubishi Electric Corporation)

Model	Manufacturer part no.
LJ1-1-RJ-05	MR-JRCBL5M-H (motor/encoder/brake)

*1 When the Matsushita Electric Industrial Co., Ltd. motor driver is selected, in addition to the cable, a power connector (MOLEX 5569 - 10R) and an interface connector (Sumitomo/3-M Limited 10126-3000VE) are also required.

*2 A cable is not provided for the Mitsubishi Electric Corporation motor and brake, and therefore, the customer should arrange a 4 core, 0.75mm² electric cable.

*3 When the Yaskawa Electric Corporation motor driver is selected, a digital operator and PC are required for selecting the various parameters.

Please refer to the technical literature of each manufacturer for further details.

Non-standard Motor Driver Regenerative Absorption Unit/Regenerative Resistor

This is a regenerative absorption unit and regenerative resistor for a non-standard motor. Make a selection providing an allowance beyond the calculated capacity.

How to order

LJ1 - 7 - G

Compatible model

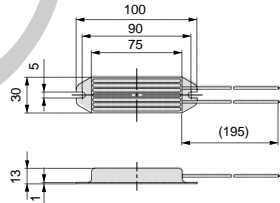
G	Matsushita Electric Industrial Co., Ltd.
R	Mitsubishi Electric Corporation
Y	Yaskawa Electric Corporation

Applicable types

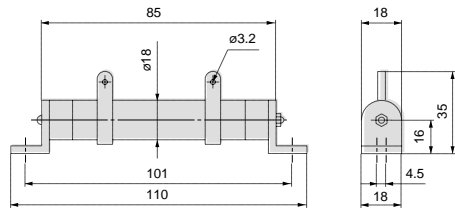
LJ1 (non-standard motor), LXP/LXS (AC servomotor)

Model	Manufacturer part no.
LJ1-7-G	DVO P0820
LJ1-7-R	MR-RB013
LJ1-7-Y	JUSP-RG08

LJ1-7-G/Matsushita Electric Industrial Co., Ltd.



LJ1-7-R/Mitsubishi Electric Corporation



LJ1-7-Y/Yaskawa Electric Corporation

